

Invariant manifolds in Hermite Sobolev spaces

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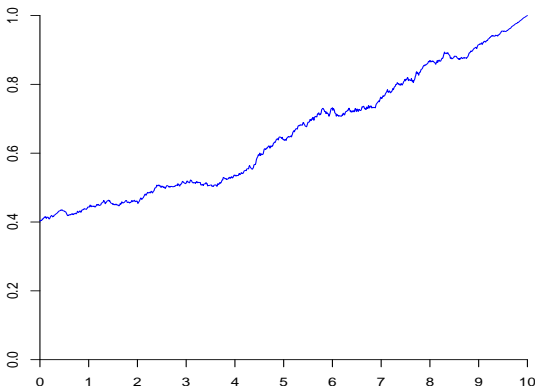
Interest rate models

- Some references:
 - 1 Björk (2004)
 - 2 Carmona & Tehranchi (2006)
 - 3 Filipović (2010)

Preliminaries

Zero Coupon Bonds

- Contracts $(P(t, T))_{0 \leq t \leq T}$.
- Ensuring one monetary unit at the date of maturity T .
- The evolution $t \mapsto P(t, T)$ is a stochastic process.



The forward rates

- Forward rates $(f(t, T))_{0 \leq t \leq T}$.
- Rates at time T regarded from today's perspective t .
- The bond prices are given by

$$P(t, T) = \exp\left(-\int_t^T f(t, s)ds\right), \quad t \leq T.$$

- HJM modeling approach: For each $T \geq 0$ we have

$$\begin{aligned} f(t, T) &= f^*(0, T) + \int_0^t \alpha(s, T)ds \\ &\quad + \int_0^t \sigma(s, T)dW_s, \quad t \in [0, T]. \end{aligned}$$

- Here W is an \mathbb{R}^r -valued Wiener process.
- See: Heath, Jarrow & Morton (1993).

Arbitrage free bond markets

- No opportunity to gain money without any risk.
- This is ensured if there exists a martingale measure $\mathbb{Q} \approx \mathbb{P}$.
- Under \mathbb{Q} , for each $T \geq 0$ we have

$$\left(\frac{P(t, T)}{B(t)} \right)_{t \in [0, T]} \in \mathcal{M}_{\text{loc}}.$$

- Here B denotes the savings account

$$B(t) = \exp \left(\int_0^t f(s, s) ds \right), \quad t \in \mathbb{R}_+.$$

- Under \mathbb{Q} , the drift term is given by the HJM drift condition

$$\alpha_{\text{HJM}}(t, T) = \sum_{j=1}^r \sigma^j(t, T) \int_t^T \sigma^j(t, s) ds.$$

The HJMM equation

From HJM to stochastic equations

- We perform the *Musiela parametrization*

$$r_t(x) := f(t, t+x) \quad \text{for } t, x \in \mathbb{R}_+.$$

- See: Musiela (1993).
- Then we arrive at the *HJMM equation*

$$\begin{cases} dr_t &= \left(\frac{d}{dx} r_t + \alpha_{\text{HJM}}(r_t) \right) dt + \sigma(r_t) dW_t \\ r_0 &= h_0. \end{cases} \quad (1)$$

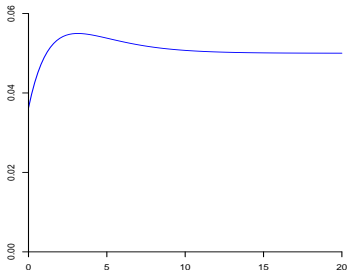
- The drift is given by the HJM drift condition

$$\alpha_{\text{HJM}}(h) = \sum_{j=1}^{\infty} \sigma^j(h) \int_0^\bullet \sigma^j(h)(\eta) d\eta. \quad (2)$$

- This is a SPDE in the framework of the semigroup approach.

The HJMM equation

- Now H and U are separable Hilbert spaces.
- Let W be an U -valued Q -Wiener process for some self-adjoint operator $Q \in L_1^{++}(U)$.
- We have $\sigma : H \rightarrow L_2^0(H)$.
- $\alpha_{\text{HJM}} : H \rightarrow H$ is given by the HJM drift condition (2).
- State space H of functions $h : \mathbb{R}_+ \rightarrow \mathbb{R}$.



The space of forward curves

- For $\beta > 0$ we define the separable Hilbert space

$$H_\beta := \{h : \mathbb{R}_+ \rightarrow \mathbb{R} : h \text{ is absolutely continuous and } \|h\|_\beta < \infty\}.$$

- The norm is given by

$$\|h\|_\beta := \left(|h(0)|^2 + \int_{\mathbb{R}_+} |h'(x)|^2 e^{\beta x} dx \right)^{1/2} < \infty.$$

- $(S_t)_{t \geq 0}$ is the translation semigroup $S_t h = h(t + \bullet)$.
- The translation semigroup $(S_t)_{t \geq 0}$ is a C_0 -semigroup on H_β .
- The infinitesimal generator is the differential operator d/dx .
- The domain of d/dx is given by

$$D(d/dx) = \{h \in H_\beta : h' \in H_\beta\}.$$

- See: Filipović (2001).

Existence of mild solutions

- Suppose there are constants $L_\sigma, M_\sigma > 0$ such that

$$\begin{aligned}\|\sigma(h) - \sigma(g)\|_{L_2^0(H_\beta)} &\leq L_\sigma \|h - g\|_\beta, \quad h, g \in H_\beta, \\ \|\sigma(h)\|_{L_2^0(H_\beta)} &\leq M_\sigma, \quad h \in H_\beta.\end{aligned}$$

- Then there are constants $L_\alpha, M_\alpha > 0$ such that

$$\begin{aligned}\|\alpha_{\text{HJM}}(h) - \alpha_{\text{HJM}}(g)\|_\beta &\leq L_\alpha \|x - y\|_\beta, \\ \|\alpha_{\text{HJM}}(h)\|_\beta &\leq M_\alpha.\end{aligned}$$

- Existence and uniqueness of mild solutions.
- Some references:
 - 1 Filipović (2001).
 - 2 Filipović & Tappe (2008).
 - 3 Filipović, Tappe & Teichmann (2010).

Invariant manifolds and finite dimensional realizations

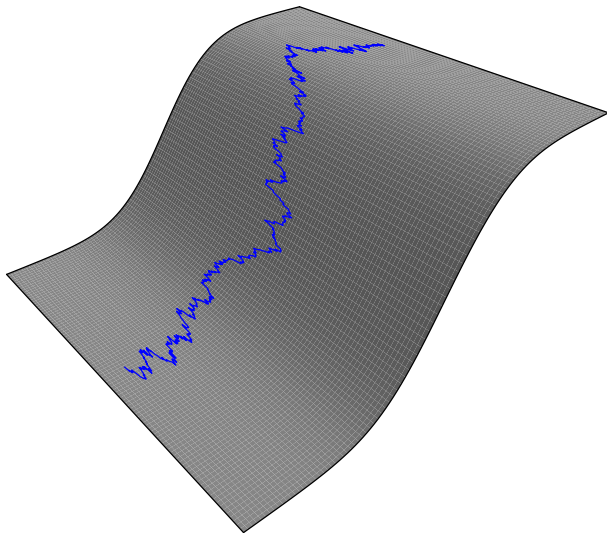
- Consider an H -valued SPDE

$$\begin{cases} dr_t &= (Ar_t + \alpha(r_t))dt + \sigma(r_t)dW_t \\ r_0 &= h_0. \end{cases} \quad (3)$$

- Let \mathcal{M} be a finite dimensional C^2 -submanifold of H .
- \mathcal{M} is called *locally invariant* for the SPDE (3) if for each $h_0 \in \mathcal{M}$ there exists a local mild solution r with $r_0 = h_0$ such that $r^\tau \in \mathcal{M}$ for some stopping time $\tau > 0$.
- The SPDE (3) has a finite dimensional realization (FDR) if for each h_0 there exists an invariant manifold \mathcal{M} with $h_0 \in \mathcal{M}$.

Illustration

- Trajectory on an invariant submanifold:



An invariance result

- We assume that $\sigma^j \in C^1(H)$ for each $j \in \mathbb{N}$.
- Then \mathcal{M} is locally invariant if and only if

$$\mathcal{M} \subset D(A),$$

$$\sigma^j(h) \in T_h\mathcal{M}, \quad h \in \mathcal{M} \text{ and } j \in \mathbb{N},$$

$$Ah + \alpha(h) - \frac{1}{2} \sum_{j \in \mathbb{N}} D\sigma^j(h)\sigma^j(h) \in T_h\mathcal{M}, \quad h \in \mathcal{M}.$$

- References:
 - Filipović (2000).
 - Nakayama (2004).
 - Filipović, Tappe & Teichmann (2014).

- There are several models with an affine realization; e.g.:

① Ho-Lee model: $\sigma(h) = c \cdot \mathbb{1}$.

② Vasiček model: $\sigma(h) = c \cdot e^{-\gamma \bullet}$.

③ Cox-Ingersoll-Ross model: $\sigma(h) = \rho \sqrt{|h(0)|} \lambda$, where

$$\frac{d}{dx} \lambda + \rho^2 \lambda \Lambda + \gamma \lambda = 0, \quad \lambda(0) = 1.$$

- References:

① Björk & Svensson (2001), Björk & Landén (2002).

② Filipović & Teichmann (2003, 2004).

③ Tappe (2010, 2012, 2016).

④ Platen & Tappe (2015).

Invariant manifolds for SPDEs in continuously embedded Hilbert spaces

- Main reference: Bhaskaran & Tappe (2021).

Invariant manifolds in finite dimension

- Consider the \mathbb{R}^d -valued SDE

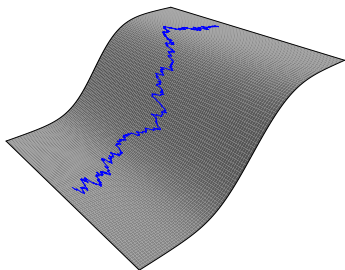
$$\begin{cases} dX_t &= b(X_t)dt + \sigma(X_t)dW_t \\ X_0 &= x_0. \end{cases} \quad (4)$$

- Here $x_0 \in \mathbb{R}^d$ is the starting point.
- We consider measurable mappings

$$b : \mathbb{R}^d \rightarrow \mathbb{R}^d \quad \text{and} \quad \sigma : \mathbb{R}^d \rightarrow \mathbb{R}^{d \times r}.$$

- W is an \mathbb{R}^r -valued standard Wiener process.

- Let \mathcal{M} be an m -dimensional C^2 -submanifold of \mathbb{R}^d ($m \leq d$).
- \mathcal{M} is called *locally invariant* for the SDE (4) if for each $x_0 \in \mathcal{M}$ there exists a local weak solution (\mathbb{B}, W, X) with $X_0 = x_0$ such that $X^\tau \in \mathcal{M}$ for some stopping time $\tau > 0$.
- Trajectory on an invariant submanifold:



- Recall the \mathbb{R}^d -valued SDE

$$\begin{cases} dX_t &= b(X_t)dt + \sigma(X_t)dW_t \\ X_0 &= x_0. \end{cases} \quad (5)$$

- We assume that $b \in C(\mathbb{R}^d; \mathbb{R}^d)$ and $\sigma \in C^1(\mathbb{R}^d; \mathbb{R}^{d \times r})$.
- \mathcal{M} is locally invariant for the SDE (5) if and only if

$$b(x) - \frac{1}{2} \sum_{j=1}^r D\sigma^j(x)\sigma^j(x) \in T_x\mathcal{M},$$
$$\sigma^1(x), \dots, \sigma^r(x) \in T_x\mathcal{M}$$

for all $x \in \mathcal{M}$.

Stochastic partial differential equations and invariant manifolds

Continuously embedded Hilbert spaces

- Let $(G, \langle \cdot, \cdot \rangle_G)$ and $(H, \langle \cdot, \cdot \rangle_H)$ be Hilbert spaces.
- Then we call (G, H) *continuously embedded Hilbert spaces* if:
 - 1 We have $G \subset H$ as sets.
 - 2 The embedding operator $\text{Id} : (G, \|\cdot\|_G) \rightarrow (H, \|\cdot\|_H)$ is continuous; that is, there is a constant $K > 0$ such that

$$\|x\|_H \leq K\|x\|_G \quad \text{for all } x \in G.$$

- In the sequel, we are interested in *continuous* mappings

$$A : (G, \|\cdot\|_G) \rightarrow (H, \|\cdot\|_H).$$

Stochastic partial differential equations

- Let (G, H) be continuously embedded Hilbert spaces.
- We assume that G and H are separable.
- Consider the SPDE

$$\begin{cases} dY_t &= L(Y_t)dt + A(Y_t)dW_t \\ Y_0 &= y_0. \end{cases} \quad (6)$$

- Here $y_0 \in G$ is the starting point.
- Moreover, we consider continuous mappings

$$L : G \rightarrow H \quad \text{and} \quad A^1, \dots, A^r : G \rightarrow H.$$

- A triplet (\mathbb{B}, W, Y) is called a local *martingale solution* to the SPDE (6) with $Y_0 = y_0$ if:
 - 1 $\mathbb{B} = (\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$ is a stochastic basis.
 - 2 W is an \mathbb{R}^r -valued standard Wiener process on \mathbb{B} .
 - 3 Y is a G -valued adapted process on \mathbb{B} such that for some stopping time $\tau > 0$ we have \mathbb{P} -almost surely

$$Y_{t \wedge \tau} = y_0 + \underbrace{\int_0^{t \wedge \tau} L(Y_s) ds}_{\text{in } (H, \|\cdot\|_H)} + \underbrace{\int_0^{t \wedge \tau} A(Y_s) dW_s}_{\text{in } (H, \|\cdot\|_H)}, \quad t \in \mathbb{R}_+.$$

- $Y_t : (\Omega, \mathcal{F}_t) \rightarrow (G, \mathcal{B}(H)_G)$ is measurable for every $t \in \mathbb{R}_+$.
- By Kuratowski's theorem we have $\mathcal{B}(G) = \mathcal{B}(H)_G$.
- The existence of martingale solutions is unclear.

Submanifolds in Hilbert spaces

- Let H be a Hilbert space and $m, k \in \mathbb{N}$.
- Let \mathcal{M} be an m -dimensional C^k -submanifold of H .
- That is, for every $y \in \mathcal{M}$ there are an open neighborhood $U \subset H$ of y , an open set $V \subset \mathbb{R}^m$ and a mapping $\phi \in C^k(V; H)$ such that:
 - 1 $\phi: V \rightarrow U \cap \mathcal{M}$ is a homeomorphism.
 - 2 $D\phi(x) \in L(\mathbb{R}^m, H)$ is one-to-one for each $x \in V$.
- ϕ is called a local *parametrization* of \mathcal{M} around y .

- The *tangent space* of \mathcal{M} at a point $y \in \mathcal{M}$ is

$$T_y\mathcal{M} := D\phi(x)(\mathbb{R}^m), \quad \text{where } x = \phi^{-1}(y).$$

- $\phi : V \rightarrow U \cap \mathcal{M}$ is a parametrization of \mathcal{M} around y .
- A mapping $A : \mathcal{M} \rightarrow H$ is called a *vector field* on \mathcal{M} if

$$A(y) \in T_y\mathcal{M}, \quad y \in \mathcal{M}.$$

- Let $\Gamma(T\mathcal{M})$ be the space of all vector fields on \mathcal{M} .

Submanifolds in continuously embedded Hilbert spaces

- Let (G, H) be continuously embedded Hilbert spaces.
- We call \mathcal{M} a (G, H) -submanifold of class C^k if:
 - ① We have $\mathcal{M} \subset G$ as sets.
 - ② Each parametrization ϕ is also a homeomorphism

$$\phi : V \rightarrow (U \cap \mathcal{M}, \|\cdot\|_G).$$

This is satisfied if and only if

$$\text{Id} : (\mathcal{M}, \|\cdot\|_H) \rightarrow (\mathcal{M}, \|\cdot\|_G)$$

is a homeomorphism.

- In this case \mathcal{M} is a topological submanifold of G .

- Let (G, H) be continuously embedded Hilbert spaces.
- We assume that G and H are separable.
- Consider the SPDE

$$\begin{cases} dY_t &= L(Y_t)dt + A(Y_t)dW_t \\ Y_0 &= y_0. \end{cases} \quad (7)$$

- Let \mathcal{M} an m -dimensional (G, H) -submanifold of class C^k .
- \mathcal{M} is called *locally invariant* for the SPDE (7) if for each $y_0 \in \mathcal{M}$ there is a local martingale solution (\mathbb{B}, W, Y) with $Y_0 = y_0$ such that $Y^\tau \in \mathcal{M}$ for some stopping time $\tau > 0$.

The generalized correction term

- For $A, B \in \Gamma(T\mathcal{M})$ we define the correction term

$$[A, B] \in A(\mathcal{M})/\Gamma(T\mathcal{M}).$$

- Here $A(\mathcal{M})$ is the space of all mappings $A : \mathcal{M} \rightarrow H$.
- For each parametrization $\phi : V \rightarrow U \cap \mathcal{M}$ a local representative of $[A, B]$ is given by

$$y \mapsto D^2\phi(x)(D\phi(x)^{-1}A(y), D\phi(x)^{-1}B(y)), \quad y \in U \cap \mathcal{M},$$

where $x = \phi^{-1}(y) \in V$.

- If $A \in C^1(H)$ and $B \in C(H)$, then we have

$$[A, B] = [DA \cdot B]_{\Gamma(T\mathcal{M})}.$$

The invariance result

- We assume that $L, A^1, \dots, A^r : G \rightarrow H$ are continuous.
- Let \mathcal{M} be an m -dimensional (G, H) -submanifold of class C^2 .

Theorem:

\mathcal{M} is locally invariant for the SPDE

$$\begin{cases} dY_t &= L(Y_t)dt + A(Y_t)dW_t \\ Y_0 &= y_0 \end{cases}$$

if and only if

$$A^j|_{\mathcal{M}} \in \Gamma(T\mathcal{M}), \quad j = 1, \dots, r,$$

$$[L|_{\mathcal{M}}]_{\Gamma(T\mathcal{M})} = \frac{1}{2} \sum_{j=1}^r [A^j|_{\mathcal{M}}, A^j|_{\mathcal{M}}].$$

Semilinear SPDEs

- We consider the H -valued SPDE

$$\begin{cases} dY_t &= (AY_t + \alpha(Y_t))dt + \sigma(Y_t)dW_t \\ Y_0 &= y_0. \end{cases} \quad (8)$$

- Here $A : H \supset D(A) \rightarrow H$ is a densely defined, closed operator.
- Furthermore $\alpha, \sigma^1, \dots, \sigma^r : H \rightarrow H$ are continuous.
- A local *analytically weak martingale solution* (\mathbb{B}, W, Y) is defined similar as a local martingale solution, but now we require that for all $\zeta \in D(A^*)$ we have \mathbb{P} -almost surely

$$\begin{aligned} \langle \zeta, Y_t \rangle_H &= \langle \zeta, y_0 \rangle_H + \int_0^t (\langle A^* \zeta, Y_s \rangle_H + \langle \zeta, \alpha(Y_s) \rangle_H) ds \\ &\quad + \int_0^t \langle \zeta, \sigma(Y_s) \rangle_H dW_s, \quad t \in \mathbb{R}_+. \end{aligned}$$

An invariance result

- $(D(A), H)$ are continuously embedded Hilbert spaces, where

$$\|y\|_{D(A)} = \sqrt{\|y\|_H^2 + \|Ay\|_H^2}, \quad y \in D(A).$$

Proposition:

For a C^2 -submanifold \mathcal{M} of H the following are equivalent:

- 1 \mathcal{M} is weakly locally invariant for the SPDE (8).
- 2 \mathcal{M} is a $(D(A), H)$ -submanifold, which is locally invariant for the SPDE (8).
- 3 \mathcal{M} is a $(D(A), H)$ -submanifold, and we have

$$\sigma^j \in \Gamma(T\mathcal{M}), \quad j = 1, \dots, r,$$

$$[(A + \alpha)|_{\mathcal{M}}]_{\Gamma(T\mathcal{M})} = \frac{1}{2} \sum_{j=1}^r [\sigma^j|_{\mathcal{M}}, \sigma^j|_{\mathcal{M}}].$$

Remarks on the regularity

- Let $k, l \in \mathbb{N}_0$ be such that:
 - ① \mathcal{M} is a C^k -submanifold of H .
 - ② $\sigma^j \in C^l(H)$ for all $j = 1, \dots, r$.
- Assumption in Filipović (2000): $k = 2$ and $l = 1$.
- Assumption in Nakayama (2004): $k = 1$ and $l = 1$.
- In this presentation we assume: $k = 2$ and $l = 0$.
- At any rate, we have

$$k + l \geq 2.$$

Quasi-linear SPDEs

- Consider continuously embedded Hilbert spaces

$$(H_0, H_1, \dots, H_{k-1}, H_k).$$

- Let \mathcal{M} be a (H_0, H_k) -submanifold of class C^k .
- Then we call \mathcal{M} a (H_0, \dots, H_k) -submanifold of class C^k if \mathcal{M} is also a (H_0, H_l) -submanifold of class C^l for $l = 1, \dots, k - 1$.
- Then for every parametrization $\phi : V \rightarrow U \cap \mathcal{M}$ of the C^k -submanifold \mathcal{M} we have

$$\phi \in \bigcap_{l=0}^k C^l(V; H_l).$$

- Let (G, H) be continuously embedded Hilbert spaces.
- Recall the SPDE

$$\begin{cases} dY_t &= L(Y_t)dt + A(Y_t)dW_t \\ Y_0 &= y_0. \end{cases} \quad (9)$$

- Existence of a continuous maps $\bar{A}^j : G \times G \rightarrow H$ such that

$$\begin{aligned} A^j(y) &= \bar{A}^j(y, y), \quad y \in G, \\ \bar{A}_z^j &:= \bar{A}^j(\cdot, z) \in L(G, H), \quad z \in G \end{aligned}$$

for all $j = 1, \dots, r$.

Stronger invariance conditions

- Let \mathcal{M} be an m -dimensional (G, H) -submanifold of class C^2 .

Corollary:

Suppose that

$$\bar{A}_z^j|_{\mathcal{M}} \in \Gamma_z^{\text{loc}}(T\mathcal{M}), \quad z \in \mathcal{M}, \quad j = 1, \dots, r, \quad (10)$$

$$[L|_{\mathcal{M}}]_{\Gamma(T\mathcal{M})} = \frac{1}{2} \sum_{j=1}^r [A^j|_{\mathcal{M}}, A^j|_{\mathcal{M}}]. \quad (11)$$

Then \mathcal{M} is locally invariant for the SPDE (9).

- Here $\Gamma_z^{\text{loc}}(T\mathcal{M})$ denotes the space of local vector fields around z .
- Note that (10) implies that $A^j \in \Gamma(T\mathcal{M})$.

Simplification of the invariance conditions

- Let H_0 be another separable Hilbert space such that (G, H_0, H) are continuously embedded Hilbert spaces.
- Assume that \mathcal{M} is a (G, H_0, H) -submanifold of class C^2 .
- Suppose that for all $j = 1, \dots, r$ and $z \in \mathcal{M}$ we have

$$\bar{A}_z^j \in L(H_0, H) \quad \text{and} \quad \bar{A}_z^j|_G \in L(G, H_0).$$

Proposition:

If condition (10) holds, then (11) is equivalent to

$$L|_{\mathcal{M}} - \frac{1}{2} \sum_{j=1}^r \bar{A}^j(A^j(\cdot), \cdot)|_{\mathcal{M}} \in \Gamma(T\mathcal{M}). \quad (12)$$

Hermite Sobolev spaces

- Some references:
 - 1 Bhar (2015).
 - 2 Itô (1984).
 - 3 Kallianpur & Xiong (1995).

The Schwartz space

- A function $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$ is called *rapidly decreasing* if

$$\lim_{|x| \rightarrow \infty} x^\alpha \varphi(x) = 0 \quad \text{for all } \alpha \in \mathbb{N}_0^d.$$

- The *Schwartz space* $\mathcal{S}(\mathbb{R}^d)$ is defined as

$$\mathcal{S}(\mathbb{R}^d) = \{\varphi \in C^\infty(\mathbb{R}^d) : D^\beta \varphi \text{ rapidly decreasing for all } \beta \in \mathbb{N}_0^d\}.$$

- Fréchet space with respect to the seminorms

$$p_{\alpha,m}(\varphi) := \sup_{x \in \mathbb{R}^d} (1 + |x|^m) |(D^\alpha \varphi)(x)|.$$

The space of tempered distributions

- The *space of tempered distributions* is its dual space

$$\mathcal{S}'(\mathbb{R}^d).$$

- Let $f \mapsto T_f : \mathcal{S}(\mathbb{R}^d) \rightarrow \mathcal{S}'(\mathbb{R}^d)$ be the linear operator

$$T_f(\varphi) := \int_{\mathbb{R}^d} f(x)\varphi(x)dx, \quad \varphi \in \mathcal{S}(\mathbb{R}^d).$$

- This provides an embedding

$$\mathcal{S}(\mathbb{R}^d) \hookrightarrow \mathcal{S}'(\mathbb{R}^d).$$

- The Hermite functions $\{h_n : n \in \mathbb{N}_0^d\}$ are an ONB of $L^2(\mathbb{R}^d)$.
- For $p \in \mathbb{R}$ and $\varphi, \psi \in \mathcal{S}(\mathbb{R}^d)$ we set

$$\langle \varphi, \psi \rangle_p := \sum_{k=0}^{\infty} \sum_{|n|=k} (2k+d)^{2p} \langle \varphi, h_n \rangle_{L^2} \langle h_n, \psi \rangle_{L^2}.$$

- We define the *Hermite Sobolev space*

$$\mathcal{S}_p(\mathbb{R}^d) := \overline{\mathcal{S}(\mathbb{R}^d)}^{\|\cdot\|_p} \subset \mathcal{S}'(\mathbb{R}^d).$$

- Separable Hilbert spaces $(\mathcal{S}_p(\mathbb{R}^d))_{p \in \mathbb{R}}$ such that

$$\mathcal{S}(\mathbb{R}^d) \subset \mathcal{S}_p(\mathbb{R}^d) \subset \mathcal{S}'(\mathbb{R}^d) \quad \text{for each } p \in \mathbb{R}.$$

- For $p \leq q$ we have Hilbert spaces with continuous embedding

$$(\mathcal{S}_q(\mathbb{R}^d), \mathcal{S}_p(\mathbb{R}^d)).$$

- For $q \leq 0 \leq p$ we have

$$\underbrace{\mathcal{S}(\mathbb{R}^d) \subset \mathcal{S}_p(\mathbb{R}^d) \subset \mathcal{S}_0(\mathbb{R}^d) = L^2(\mathbb{R}^d)}_{\text{functions}} \subset \underbrace{\mathcal{S}_q(\mathbb{R}^d) \subset \mathcal{S}'(\mathbb{R}^d)}_{\text{distributions}}.$$

- For $k \in \mathbb{N}_0$ and $p > \frac{d}{4} + \frac{k}{2}$ we have

$$\mathcal{S}_p(\mathbb{R}^d) \subset C_0^k(\mathbb{R}^d).$$

- Let $p \in \mathbb{R}$ be arbitrary.
- The inner product

$$\langle \cdot, \cdot \rangle_{L^2} : \mathcal{S}(\mathbb{R}^d) \times \mathcal{S}(\mathbb{R}^d) \rightarrow \mathbb{R}$$

extends to a continuous bilinear mapping

$$\langle \cdot, \cdot \rangle : \mathcal{S}_{-p}(\mathbb{R}^d) \times \mathcal{S}_p(\mathbb{R}^d) \rightarrow \mathbb{R}.$$

- We obtain the dual pair

$$(\mathcal{S}_{-p}(\mathbb{R}^d), \mathcal{S}_p(\mathbb{R}^d), \langle \cdot, \cdot \rangle).$$

- For $x \in \mathbb{R}^d$ we define $\delta_x \in \mathcal{S}'(\mathbb{R}^d)$ as

$$\langle \delta_x, \varphi \rangle := \varphi(x), \quad \varphi \in \mathcal{S}(\mathbb{R}^d).$$

- Rajeev & Thangavelu (2008): We have

$$\delta_x \in \mathcal{S}_p(\mathbb{R}^d) \quad \text{for all } p < -\frac{d}{4}.$$

- Let μ be a finite signed measure on $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d))$.
- By identification we have $\mu \in \mathcal{S}'(\mathbb{R}^d)$, where

$$\langle \mu, \varphi \rangle = \int_{\mathbb{R}^d} \varphi(x) \mu(dx), \quad \varphi \in \mathcal{S}(\mathbb{R}^d).$$

- With this convention, we have

$$\mu \in \mathcal{S}_p(\mathbb{R}^d) \quad \text{for all } p < -\frac{d}{4}.$$

- Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a polynomial of several variables.
- By identification we have $f \in \mathcal{S}'(\mathbb{R}^d)$, where

$$\langle f, \varphi \rangle = \int_{\mathbb{R}^d} f(x)\varphi(x)dx, \quad \varphi \in \mathcal{S}(\mathbb{R}^d).$$

- With $n = \deg(f)$ we have

$$f \in \mathcal{S}_p(\mathbb{R}^d) \quad \text{for all } p < -\frac{d}{4} - \frac{n}{2}.$$

The differential operator

- Let $i \in \{1, \dots, d\}$ be arbitrary.
- We define $\partial_i : \mathcal{S}'(\mathbb{R}^d) \rightarrow \mathcal{S}'(\mathbb{R}^d)$ by duality as

$$\langle \partial_i \Phi, \varphi \rangle := -\langle \Phi, \partial_i \varphi \rangle, \quad (\Phi, \varphi) \in \mathcal{S}'(\mathbb{R}^d) \times \mathcal{S}(\mathbb{R}^d).$$

- For each $p \in \mathbb{R}$ we have

$$\partial_i|_{\mathcal{S}_{p+\frac{1}{2}}(\mathbb{R}^d)} \in L(\mathcal{S}_{p+\frac{1}{2}}(\mathbb{R}^d), \mathcal{S}_p(\mathbb{R}^d)).$$

The multiplication operator

- Let $i \in \{1, \dots, d\}$ be arbitrary.
- Define the *multiplication operator* $M_i : \mathcal{S}(\mathbb{R}^d) \rightarrow \mathcal{S}(\mathbb{R}^d)$ as

$$(M_i \varphi)(x) := x_i \varphi(x) \quad \text{for all } x \in \mathbb{R}^d.$$

- We extend to $M_i : \mathcal{S}'(\mathbb{R}^d) \rightarrow \mathcal{S}'(\mathbb{R}^d)$ by duality as

$$\langle M_i \Phi, \varphi \rangle := \langle \Phi, M_i \varphi \rangle, \quad (\Phi, \varphi) \in \mathcal{S}'(\mathbb{R}^d) \times \mathcal{S}(\mathbb{R}^d).$$

- For each $p \in \mathbb{R}$ we have

$$M_i|_{\mathcal{S}_{p+\frac{1}{2}}(\mathbb{R}^d)} \in L(\mathcal{S}_{p+\frac{1}{2}}(\mathbb{R}^d), \mathcal{S}_p(\mathbb{R}^d)).$$

The Hermite operator

- The *Hermite operator* $\mathbf{H} : \mathcal{S}'(\mathbb{R}^d) \rightarrow \mathcal{S}'(\mathbb{R}^d)$ is defined as

$$\mathbf{H} := |x|^2 - \Delta := \sum_{i=1}^d (M_i^2 - \partial_i^2).$$

- For each $p \in \mathbb{R}$ the Hermite operator

$$\mathbf{H}|_{\mathcal{S}_{p+1}(\mathbb{R}^d)} \in L(\mathcal{S}_{p+1}(\mathbb{R}^d), \mathcal{S}_p(\mathbb{R}^d))$$

is an isometric isomorphism.

- See: Rajeev & Thangavelu (2003).

The translations operator

- For $x \in \mathbb{R}^d$ we define $\tau_x : \mathcal{S}(\mathbb{R}^d) \rightarrow \mathcal{S}(\mathbb{R}^d)$ as

$$(\tau_x \varphi)(y) := \varphi(y - x), \quad y \in \mathbb{R}^d.$$

- We extend to $\tau_x : \mathcal{S}'(\mathbb{R}^d) \rightarrow \mathcal{S}'(\mathbb{R}^d)$ by duality as

$$\langle \tau_x \Phi, \varphi \rangle := \langle \Phi, \tau_{-x} \varphi \rangle, \quad (\Phi, \varphi) \in \mathcal{S}'(\mathbb{R}^d) \times \mathcal{S}(\mathbb{R}^d).$$

- For each $p \in \mathbb{R}$ and $\Phi \in \mathcal{S}_p(\mathbb{R}^d)$ we define the *orbit map*

$$\xi_\Phi : \mathbb{R}^d \rightarrow \mathcal{S}_p(\mathbb{R}^d), \quad \xi_\Phi(x) := \tau_x \Phi.$$

- We have $\xi_{\delta_0}(x) = \delta_x$ for all $x \in \mathbb{R}^d$.

Group property of the translations

- Let $p \in \mathbb{R}$ be arbitrary.
- $(\tau_x)_{x \in \mathbb{R}^d}$ is a *multi-parameter C_0 -group* on $\mathcal{S}_p(\mathbb{R}^d)$.
- That is, $(\tau_x)_{x \in \mathbb{R}^d}$ is a family $\tau_x \in L(\mathcal{S}_p(\mathbb{R}^d))$, $x \in \mathbb{R}^d$ with:
 - 1 $\tau_0 = \text{Id}$.
 - 2 $\tau_{x+y} = \tau_x \tau_y$ for all $x, y \in \mathbb{R}^d$.
 - 3 ξ_Φ is continuous for each $\Phi \in \mathcal{S}_p(\mathbb{R}^d)$.

The infinitesimal generator

- For $i = 1, \dots, d$ consider the C_0 -group $(\tau_y^i)_{y \in \mathbb{R}}$ given by

$$\tau_y^i := \tau_{ye_i}, \quad y \in \mathbb{R}.$$

- We denote the generator of $(\tau_y^i)_{y \in \mathbb{R}}$ by

$$A_{p,i} : \mathcal{S}_p(\mathbb{R}^d) \supset D(A_{p,i}) \rightarrow \mathcal{S}_p(\mathbb{R}^d).$$

Proposition:

The following statements are true:

- 1 We have $\mathcal{S}_{p+\frac{1}{2}}(\mathbb{R}^d) \subset D(A_{p,i})$.
- 2 $\mathcal{S}_{p+\frac{1}{2}}(\mathbb{R}^d)$ is a core for $A_{p,i}$.
- 3 We have $A_{p,i}\Phi = -\partial_i\Phi$ for each $\Phi \in \mathcal{S}_{p+\frac{1}{2}}(\mathbb{R}^d)$.

- See: Bhaskaran & Tappe (2021).

Invariant manifolds in Hermite Sobolev spaces

Submanifolds in Hermite Sobolev spaces

- Let $p \in \mathbb{R}$ be arbitrary.
- Let (G, H) be the continuously embedded Hilbert spaces

$$G := \mathcal{S}_{p+1}(\mathbb{R}^d) \quad \text{and} \quad H := \mathcal{S}_p(\mathbb{R}^d).$$

- Let \mathcal{M} be a finite dimensional C^k -submanifold of H .
- If $\mathcal{M} \subset G$, then the following statements are equivalent:
 - 1 \mathcal{M} is a (G, H) -submanifold of class C^k .
 - 2 The restriction

$$\mathbf{H}|_{\mathcal{M}} : (\mathcal{M}, \|\cdot\|_H) \rightarrow (\mathbf{H}(\mathcal{M}), \|\cdot\|_H)$$

is a homeomorphism.

Embedded submanifolds

- Let \mathcal{N} be an m -dimensional C^k -submanifold of \mathbb{R}^d . ($m \leq d$)
- Let $\psi \in C^k(\mathbb{R}^d; H)$ be one-to-one.
- Let \mathcal{M} be an m -dimensional C^k -submanifold of H .
- \mathcal{M} is called *embedded* by (ψ, \mathcal{N}) if for each $y \in \mathcal{M}$ there exist $x \in \mathcal{N}$ with $\psi(x) = y$ and a local parametrization $\varphi: V \rightarrow X \cap \mathcal{N}$ around x such that

$$\phi := \psi \circ \varphi: V \rightarrow U \cap \mathcal{M}$$

is a local parametrization around y .

- Illustration of the definition:

$$\begin{array}{ccc} X \cap \mathcal{N} & \xrightarrow{\psi} & U \cap \mathcal{M} \\ \varphi \uparrow & \nearrow \phi & \\ V & & \end{array}$$

A criterion for embedded submanifolds

- Let $\psi \in C^k(\mathbb{R}^d; H)$ be an injective C^k -immersion on \mathcal{N} .
- This means that

$$D\psi(x)|_{T_x\mathcal{N}} \in L(T_x\mathcal{N}, H)$$

is one-to-one for each $x \in \mathcal{N}$.

- Assume that $\psi|_{\mathcal{N}} : \mathcal{N} \rightarrow \psi(\mathcal{N})$ is a homeomorphism.
- If \mathcal{N} has one chart, then the image

$$\mathcal{M} := \psi(\mathcal{N})$$

is a C^k -submanifold of H embedded by (ψ, \mathcal{N}) .

- Let $p \in \mathbb{R}$ and $k \in \mathbb{N}$ be arbitrary.
- Let \mathcal{N} be a C^k -submanifold of \mathbb{R}^d with one chart.
- We will construct appropriate $\Phi \in \mathcal{S}_{p+\frac{k}{2}}(\mathbb{R}^d)$ such that

$$\mathcal{M} := \psi(\mathcal{N})$$

is an m -dimensional $(\mathcal{S}_{p+\frac{k}{2}}(\mathbb{R}^d), \dots, \mathcal{S}_p(\mathbb{R}^d))$ -submanifold of class C^k with one chart, which is embedded by (ψ, \mathcal{N}) .

- Here $\psi := \xi_\Phi : \mathbb{R}^d \rightarrow \mathcal{S}_{p+\frac{k}{2}}(\mathbb{R}^d)$ is the orbit map.

Distributions given by measures

- We assume that that $p + \frac{k}{2} < -\frac{d}{4}$.
- Let μ be a finite signed measure on $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d))$.
- Suppose μ has compact support and $\mu(\mathbb{R}^d) \neq 0$.
- We define the distribution $\Phi := \mu$.
- This includes the Dirac distributions

$$\Phi = \delta_x, \quad x \in \mathbb{R}^d.$$

Distributions given by polynomials

- We assume that $p + \frac{k}{2} < -\frac{d}{4} - \frac{n}{2}$ for some $m \leq n \leq d$.
- Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be the polynomial

$$f(x) = x_1 \cdot \dots \cdot x_n, \quad x \in \mathbb{R}^d.$$

- We define the distribution $\Phi := f$.
- Moreover, suppose that $\mathcal{N} \subset \mathbb{R}^n \times \{0\}$.

Distributions given by smooth functions

- We assume that $p + \frac{k}{2} > \frac{d}{4} + \frac{1}{2}$
- Let $\Phi \in \mathcal{S}_{p+\frac{k}{2}}(\mathbb{R}^d)$ be arbitrary.
- Then we have $\Phi \in C_0^1(\mathbb{R}^d)$.
- Suppose there are:
 - ① $n \in \mathbb{N}$ such that $m \leq n \leq d$,
 - ② an n -dimensional subspace $E \subset \mathbb{R}^d$ such that

$$\Gamma(T\mathcal{N}) \subset \mathcal{N} \times E,$$

- ③ elements $v_1, \dots, v_n \in E$ and $\xi_1, \dots, \xi_n \in \mathbb{R}^d$ such that

$$(D_{v_i} \Phi(\xi_j))_{i,j=1,\dots,n} \in \mathbb{R}^{n \times n}$$

is invertible.

The quasi-linear SPDE

- Continuously embedded Hilbert spaces (G, H) given by

$$G = \mathcal{S}_{p+1}(\mathbb{R}^d) \text{ and } H = \mathcal{S}_p(\mathbb{R}^d) \text{ for some } p \in \mathbb{R}.$$

- Consider the quasi-linear SPDE

$$\begin{cases} dY_t = L(Y_t)dt + A(Y_t)dW_t \\ Y_0 = y_0. \end{cases} \quad (13)$$

- The mappings $L, A^1, \dots, A^r : G \rightarrow H$ are given by

$$L(y) = \frac{1}{2} \sum_{i,j=1}^d (\langle \sigma, y \rangle \langle \sigma, y \rangle^\top)_{ij} \partial_{ij}^2 y - \sum_{i=1}^d \langle b_i, y \rangle \partial_i y,$$

$$A^j(y) = - \sum_{i=1}^d \langle \sigma_{ij}, y \rangle \partial_i y, \quad j = 1, \dots, r.$$

- Here we have $b_i, \sigma_{ij} \in \mathcal{S}_{-(p+1)}(\mathbb{R}^d)$.

Submanifolds in Hermite Sobolev spaces

- Let $\Phi \in G$ be arbitrary.
- We consider the orbit map $\psi := \xi_\Phi : \mathbb{R}^d \rightarrow G$.
- Let \mathcal{N} be an m -dimensional C^2 -submanifold of \mathbb{R}^d . ($m \leq d$)
- We define the intermediate space $H_0 = \mathcal{S}_{p+\frac{1}{2}}(\mathbb{R}^d)$.
- Then (G, H_0, H) are continuously embedded Hilbert spaces.
- Let \mathcal{M} be an m -dimensional (G, H_0, H) -submanifold of class C^2 , which is embedded by (ψ, \mathcal{N}) .
- Recently, we discussed examples on the previous slides.

Proposition:

We assume that

$$\begin{aligned}\langle b, \psi \rangle|_{\mathcal{N}} &\in \Gamma(T\mathcal{N}), \\ \langle \sigma_1, \psi \rangle|_{\mathcal{N}}, \dots, \langle \sigma_r, \psi \rangle|_{\mathcal{N}} &\in \Gamma^*(T\mathcal{N}).\end{aligned}$$

Then the submanifold \mathcal{M} is locally invariant for the SPDE (13).

- Here $\Gamma^*(T\mathcal{N})$ is the space of all mappings $a : \mathcal{N} \rightarrow \mathbb{R}^d$ such that for each $x \in \mathcal{N}$ locally we have

$$a(x) \in T_x \mathcal{N} \quad \text{for all } x \in \mathcal{N}.$$

- If $m = d$, then \mathcal{N} is locally invariant for the SPDE (13).
- See also: Rajeev (2013).

Interplay between SPDEs and finite dimensional SDEs

- Consider the \mathbb{R}^d -valued SDE

$$\begin{cases} dX_t &= b(X_t)dt + \sigma(X_t)dW_t \\ X_0 &= x_0. \end{cases} \quad (14)$$

- Locally Lipschitz mappings

$$b : \mathbb{R}^d \rightarrow \mathbb{R}^d \quad \text{and} \quad \sigma : \mathbb{R}^d \rightarrow \mathbb{R}^{d \times r}.$$

- We assume that $b_i, \sigma_{ij} \in \mathcal{S}_q(\mathbb{R}^d)$ for some $q > \frac{d}{4}$.
- Then we have $b_i, \sigma_{ij} \in C_0(\mathbb{R}^d)$.

- Let \mathcal{N} be an m -dimensional C^2 -submanifold of \mathbb{R}^d ($m \leq d$).

Proposition:






We assume that






$$\begin{aligned} b|_{\mathcal{N}} &\in \Gamma(T\mathcal{N}), \\ \sigma^1|_{\mathcal{N}}, \dots, \sigma^r|_{\mathcal{N}} &\in \Gamma^*(T\mathcal{N}). \end{aligned}$$





Then the submanifold \mathcal{N} is locally invariant for the SDE (14).

- For the proof we consider:
 - 1 The quasi-linear SPDE (13), where $p = -(q + 1)$.
 - 2 The m -dimensional submanifold






$$\mathcal{M} := \{\delta_x : x \in \mathcal{N}\}.$$





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